

NC Joining Module NCFR

For Joining Processes and Rotational Movement

The NC joining module NCFR Type 2161A..., consisting of two hollow-shaft motors and integrated sensors measuring force, displacement, crank angle, and torque (optional), is well-suited for use in monitored assembly and joining processes where rotary movements are involved in combination with linear movements.

- Compact design thanks to hollow-shaft motors
- Axial forces of up to 15 kN, torque of up to 50 N·m
- Maximum dynamic thanks to cutting-edge drive technology
- High speed of travel with up to 400 mm/s
- Absolute encoder for displacement and crank angle
- Optional torque sensor including amplifier

Description

Boasting integrated hollow-shaft servo motors, NC joining modules NCFR Type 2161A... set themselves apart with their compact dimensions and exceptionally low weight. This design affords both drives maximum dynamics and fully independent linear and rotational movements.

The drive motors are electrically commutated, hollow-shaft AC servo motors which are controlled by two servo controllers. Constant rotation speed, i.e. constant motion speed is guaranteed. Standard functions, such as block pressing, position pressing and force feedback controlled pressing, as well as intermediate positioning and rotation by signal, angle, torque and even torque control, are supported. The activation of the servo controllers and the analysis of the piezoelectric force sensor and the strain gauge torque sensor for both crank angle and displacement are handled by the XY monitor maXYmos NC.

The NC joining module NCFR is operated with IndraDrive servo controllers, in combination with maXYmos NC Type 5847B1. The communication between the servo controllers and maXYmos NC is done in real-time via SERCOS III. Several field bus slave interfaces are available onboard for customer provided controlling. PROFIBUS, PROFINET, EtherNet/IP or even EtherCAT can be used with the maXYmos NC according to the customer's selection. Quality data can be transmitted via the Ethernet interface by different protocols and a visualization via VNC® or a data backup can be performed.





Application

The NC joining module NCFR Type 2161A... is well-suited for use as a linear acuator, as well as rotational movements during assembly and joining tasks in automatic production systems.

The installation is possible both vertically and horizontally. Fixation of the joining units at a machine frame is provided through flange mounting. Tapped holes for a tool receptacle are available at the plunger (Fig. 1).



Technical Data

| mm | Fig. 1 |
|------|------------------------------------|
| | flange assembly |
| kg | 31 |
| kg | 25 ⁶ |
| | compression/tension |
| kN | 5, 15 |
| | absolute encoder |
| mm | 0,001 |
| mm | 0,01 |
| mm | 400 |
| mm | Fig. 1 |
| V/A | 24/1 |
| V/A | 24/1 |
| mm/s | 4004) |
| | piezoelectric |
| %FSO | ≤1 |
| % | 0,5 |
| | kg kg kN mm mm mm v/A v/A v/A mm/s |

| - 1 | 1 | |
|--------------------------------------|---------------------------|--------------------|
| Peak torque | N⋅m | 50 |
| Maximum speed | min ⁻¹ | 1 0004) |
| Max. number of revolutions | R/absolute | 80 |
| Resolution - rotation | ٥ | 0,01 |
| Torque sensor | | Strain gage |
| Linearity - torque | %FSO | <1,5 |
| Operating life of spindle | cycles | approx. 10 million |
| (according to defined drive profile) | | |
| Short stroke | mm | ≤60 |
| Lubrication connection | | standard |
| (exterior) | | lubricating nipple |
| Temperature range | °C | 10 40 |
| Protection class | | IP54 |
| Servo Amplifier ^{2) 5)} | Bosch-Rex | croth Type 2180A |
| Standard interface | SERCOS III (internal bus) | |

| Standard Interface | SERCOS III (Internal bus) |
|-------------------------------|---------------------------|
| Evaluation Unit ³⁾ | maXYmos NC Type 5847 |
| Standard interface | PROFIBUS, PROFINET, |
| | EtherNet/ID EtherCAT |

VDC

For horizontal mounting and max. 250 min⁻¹ are max. 5 kg permissible.

In case of horizontal mounting the bending of the ram in dependance of the tool weight must be considered. The tool weight must be reduced.

Power supply

Torque

24 ±5 %

¹⁾ Possible radial forces have to be avoided independantly of the mounting orientation.

⁴⁾ In dependance on the speeds this may reduce when operating simultaneously. Additional reduction of the speeds may be necessary in dependance of the tool weight.

²⁾ Servo amplifier, see data sheet 003-125 Type 2180A...

³⁾ Evaluation unit maXYmos NC Type 5847B... see data sheet 003-272

⁵⁾ Safety function SMES

⁶⁾ Max. moment of inertia 0,25 kg·m² /Balance quality of tool: 6.3



Dimensions NC Joining Module NCFR

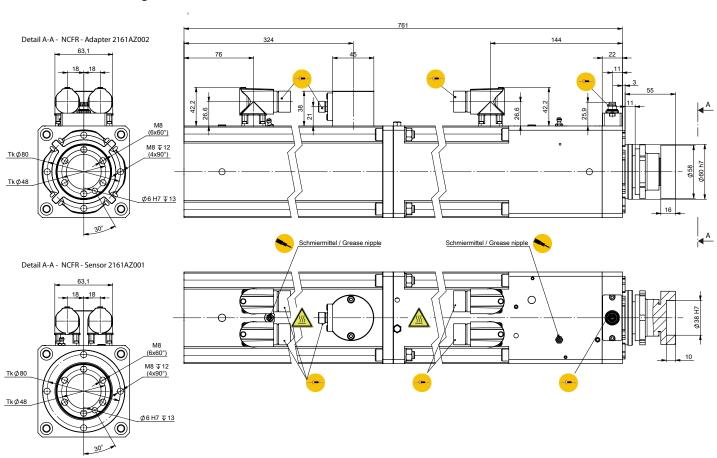


Fig. 1: Dimension NC Joining Module NCFR Type 2161A...

The radial forces (due to the weight of the tool, for example) must be considered for the installation. An external guide may have to be provided for the ram.

Warnings and Notes:

Lubrication points

Electrical connection points

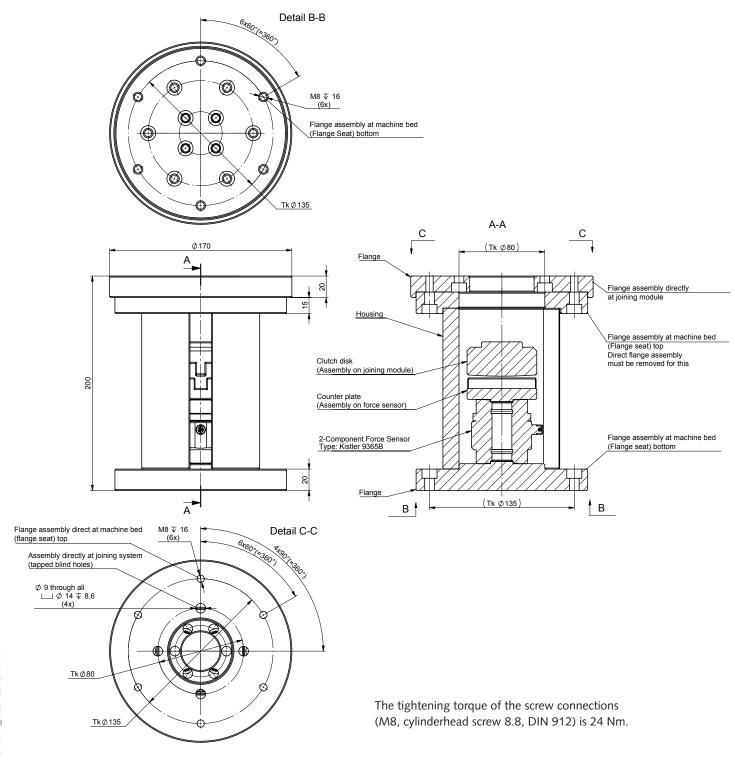
Marning high temperatures

Attachment points

Page 3/6

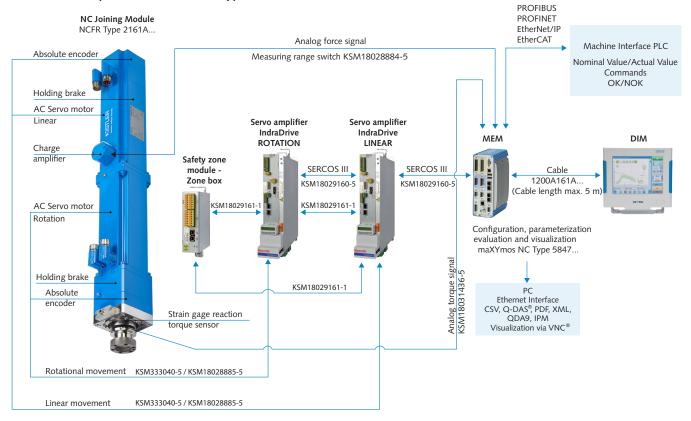


Calibration Device with Mounting Holes





Functional Principle with maXYmos NC Type 5847...



Cable

Fig. 2: Functional principle of NC joining system with NC joining module NCFR Type 2161A... and maXYmos NC Type 5847...

Included Accessories

None

| Optional Accessories • Evaluation unit maXYmos NC ¹⁾ (MEM) | Type/Art. No. 5847B1 |
|---|----------------------|
| NCFR Firmware Version | J047 BT |
| (only for re-order) | 2836A |
| • Display module (DIM) with pedestal | 5877AZ000 |
| Connection cable maXYmos | |
| MEM on DIM, length 5 m | 1200A161A5 |
| • Servo amplifier ²⁾ | 2180A |
| DIM Cable Extender | 1200A163 |
| Mounting rail adapter for 35 mm | |
| cap rail including 2 fastening | |
| screws M3x10 | 5700A31 |
| Torque Sensor | 2161AZ001 |
| Adapter Flange | 2161AZ002 |
| | |

 $^{^{\}mbox{\tiny 1)}}$ Evaluation unit maXYmos NC Type 5847B... see data sheet 003-272

| | .,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,, |
|--|---|
| NCFH motor cable, | |
| (2 cables required), length 5 m | KSM333040-5 |
| NCFH feedback cable, | |
| (2 cables required), length 5 m | KSM18028885-5 |
| maXYmos force transmitter cable, | |
| length 5 m | KSM18028884-5 |
| SERCOS III connection cable, | |
| (2 cables required), length 5 m | KSM18029160-5 |
| Safety zone box cable, | |
| (3 cables required), length 1 m | KSM18029161-1 |
| maXYmos torque | |
| transmitter cable, length 5 m | KSM18031436-5 |
| | |

Type/Art. No.

Additional lengths available upon request.

Ordering Key Servo Amplifier for NCFR

| | 6, | | Туре 2180А 🗌 |
|----------|-------------------------|------------------------|--------------|
| Power se | ection for NC joining m | odule | ^ |
| NCFR | 2161A - Linear | NCFR1LSB ⁵⁾ | |
| NCFR | 2161A - Rotation | NCFR1R00 ⁵⁾ | |

⁵⁾ Safety function SMES

Page 5/6

 $^{^{\}scriptscriptstyle 2)}$ Servo amplifier Type 2180A... see data sheet 003-125



Application Example

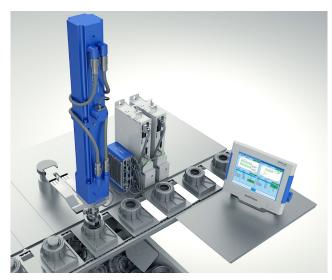
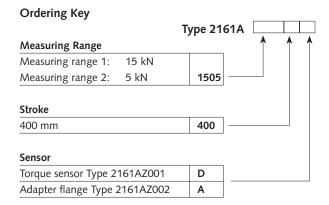


Fig. 3: Application example for joining process with NCFR and maXYmos NC



Ordering Example

Type 2161A1505400D

NC joining module NCFR **Type 2161A...**, measuring range 1: 15 kN, measuring range 2: 5 kN: **1505**, stroke: **400 mm**, sensor: torque sensor: $\bf D$